When the dual 412 device is used for A_1 , the circuit of Fig. 5-30 is suited for high-performance applications at frequencies up to 20 kHz. For higher-frequency use, a 318 device can be substituted for the two amplifiers, with a general lowering of resistances values. Both amplifiers should have good common-mode rejection. For less critical applications, a dual device, such as the 4558, can be used for both A_1 and A_2 . In such cases, it is best to keep R_3 in the range of 100 k Ω or less and the signal levels at 2 V rms or less.

5.3.7 All-Pass Circuits

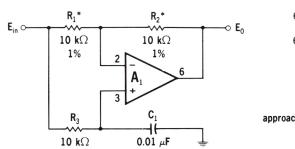
Using op-amp techniques, it is possible to alter the phase/frequency and amplitude characteristics of audio signals in a very precise and predictable manner. Phase-shifted and controlled stages are very useful tools when used in combination with other op-amp circuits. A class of active filters called *all-pass filters*, are useful for this and they exhibit a constant amplitude versus frequency characteristic.

Two circuits that exemplify the simplicity of op-amp techniques in phase manipulation are shown in Fig. 5-31. These circuits are identical except for the positions of R_3 and C_1 , which determine the lag or lead characteristics. The circuit of Fig. 5-31A operates as follows; R_3 and C_1 form a simple lag circuit with the output across C_1 applied to the reference input of A_1 . The voltage across C_1 will lag E_{in} by 45° when $X_{c_1} = R_3$, or when

$$f = \frac{1}{2\pi R_3 C_1}$$
 (Eq. 5-18)

Because of zero differential-input voltage, the voltage across C_1 must also appear at the summing point through feedback. If $R_1 = R_2$, the phase angle of the output signal will be -90° , or twice the phase angle of the signal at the summing point, with an amplitude equal to $E_{\rm in}$.

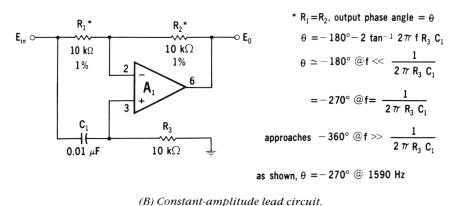
The general ability of the circuit to alter output phase for different frequencies can be appreciated by considering the relative reactances of R_3 and C_1 for different conditions. For instance, when $X_{c_1} \gg R_3$, the circuit behaves as a follower and the phase is that of the input. When X_{c_1} is $\ll R_3$, the circuit behaves as an inverter and the output phase is $-180\,^{\circ}$. These general conditions are described in the circuit notes, and the phase shift of the circuit is generally described as



*
$$R_1 = R_2$$
, output phase angle = θ $\theta = -2$ tan $^{-1}$ 2π f R_3 C_1 , $\theta \simeq 0^{\circ}$ @ f $<< \frac{1}{2\pi R_3} \frac{1}{C_1}$ $= -90^{\circ}$ @ f $= \frac{1}{2\pi R_3} \frac{1}{C_1}$ approaches -180° @ f $>> \frac{1}{2\pi R_3} \frac{1}{C_1}$

as shown, $\theta = -90^{\circ}$ @ 1590 Hz

(A) Constant-amplitude lag circuit.



$$\theta = -2 \tan^{-1} 2\pi f R_3 C_1 \qquad (Eq. 5-19)$$

The companion circuit of Fig. 5-31B is achieved by interchanging C_1 and R_3 . This circuit has the same amplitude properties as the circuit of Fig. 5-31A but, in this case, the phase shift is described as

Fig. 5-31. Constant-amplitude, phase lead/lag circuits.

$$\theta = -180^{\circ} - 2 \tan^{-1} 2\pi f R_3 C_1$$
 (Eq. 5-20)

As can be seen from the notes, this circuit behaves as an inverter at low frequencies and as a follower at very high frequencies, again due the relative reactances of C_1 and R_3 .

Perhaps the most useful function for these circuits is the generation of 90° leading or lagging signals for phase detectors and similar

circuits. The networks are easily adjustable by varying either R_3 or C_1 , and the constant amplitude output can be a great convenience. Op amps compensated for unity gain will work in this circuit, but a low input-current, high input-resistance type, such as the 34081 (or other similar FET-input unit), will allow the widest range of R_3/C_1 values. The R_1 - R_2 values are not critical but should be matched, so 10-k Ω , 1% values are suggested.

5.4 REFERENCES

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